

## Homework Assignment 3

Due: Tuesday, June 3 in class.

**There will be no extensions!**

**General remark:** Whenever you are asked to provide an  $\alpha$ -approximation algorithm, you need to prove that your algorithm outputs a feasible  $\alpha$ -approximate solution.

You can use any results that were proved in class without having to re-prove them. You can also assume, if needed, that there is an efficient algorithm for computing maximum matching in any graph.

1. **Multicut** In the Minimum Multicut problem, we are given an undirected graph  $G = (V, E)$  with weights  $w_e$  on edges  $e \in E$ . Additionally, we are given a collection  $\{(s_1, t_1), \dots, (s_k, t_k)\}$  of pairs of vertices that we would like to disconnect from each other. The goal is to find a minimum-weight subset  $E' \subseteq E$  of edges, such that, once we remove the edges of  $E'$  from  $G$ , no path connects  $s_i$  to  $t_i$  in the resulting graph, for any  $1 \leq i \leq k$ . In this question we consider the Minimum Multicut problem on star graphs (trees of height 1).
  - (a) Prove that the Minimum Multicut problem is at least as hard to approximate as Vertex Cover, even when the input graph is a star.
  - (b) Write a linear programming relaxation for the Minimum Multicut problem on a star graph, and obtain a factor 2-approximation algorithm for the problem via LP-rounding.
  - (c) Show that the integrality gap of your LP relaxation for star graphs is at least 2 asymptotically.
2. **Congestion Minimization** Show that the integrality gap of the LP-relaxation of directed Congestion Minimization is at least  $\Omega(\log n / \log \log n)$ , where  $n$  is the number of graph vertices.  
Hint: Use the construction we used in class to lower bound the integrality gap for Machine Minimization.
3. **EDP** Show exact polynomial time algorithm for the special case of the Maximum Edge Disjoint Paths problem, where the input graph is a tree. (Notice that we assume that all edge capacities are 1). Prove the algorithm's correctness.  
Hint: Use dynamic programming.
4. **Set Cover** Recall that in class we have seen a primal-dual algorithm for the Set Cover problem, whose approximation factor is  $f$ -the maximum frequency of any element (that is, the number of sets containing the element).
  - (a) Prove that the integrality gap of the LP-relaxation we have used for the Set Cover problem is at most  $f$ .
  - (b) Prove that the integrality gap of this relaxation is  $\Omega(f)$ , for any choice of the frequency value  $f$ . Hint: define an element for every  $f$ -tuple of sets.
  - (c) Does this lower bound rule out obtaining a better than factor  $\Theta(f)$ -approximation to Set Cover using the primal-dual method? Explain your answer.

5. **Multiway Cut** Consider the following generalization of the Multiway Cut problem. We are given an undirected graph  $G = (V, E)$  with costs  $w_e \geq 0$  on edges, and a subset  $T = \{t_1, \dots, t_k\}$  of vertices called terminals. Additionally, each vertex  $v \in V$  has a list  $L(v) \subsetneq T$  of *forbidden* terminals. The goal is to partition the graph vertices into  $k$  subsets  $C_1, \dots, C_k$ , such that for all  $i : 1 \leq i \leq k$ ,  $t_i \in C_i$ , and each vertex  $v \in V$  belongs to some cluster  $C_j$  with  $j \notin L(v)$ . We need to minimize the total cost of edges  $e$  whose endpoints belong to distinct subsets  $C_i$ .

- (a) Extend the LP relaxation for the multiway cut problem to this generalized setting.
- (b) Consider the following LP-rounding algorithm. At the beginning of the algorithm, all the vertices are unassigned. While there is an unassigned vertex, perform the following procedure:

Procedure Partition

For  $i = 1, 2, \dots, k$ :

- Choose  $r_i \in (0, 1)$  uniformly at random.
- For each unassigned vertex  $v$  with  $x_i(v) \geq r_i$ , assign  $v$  to  $C_i$ .

- i. Prove that the above algorithm produces a feasible solution for the generalized multiway cut problem.
- ii. Prove that the algorithm achieves an  $O(\log n)$ -approximation.  
 Hint: Bound the number of calls to Procedure Partition and bound the expected cost of each execution of the procedure.
- (c) Design a factor  $4/3$ -approximation algorithm for generalized multiway cut with  $k = 3$  terminals. (Partial credit will be given for constant factor approximation algorithm).