

Fast Maximum Margin Matrix Factorization for Collaborative Prediction

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Collaborative Prediction

Based on partially observed matrix:

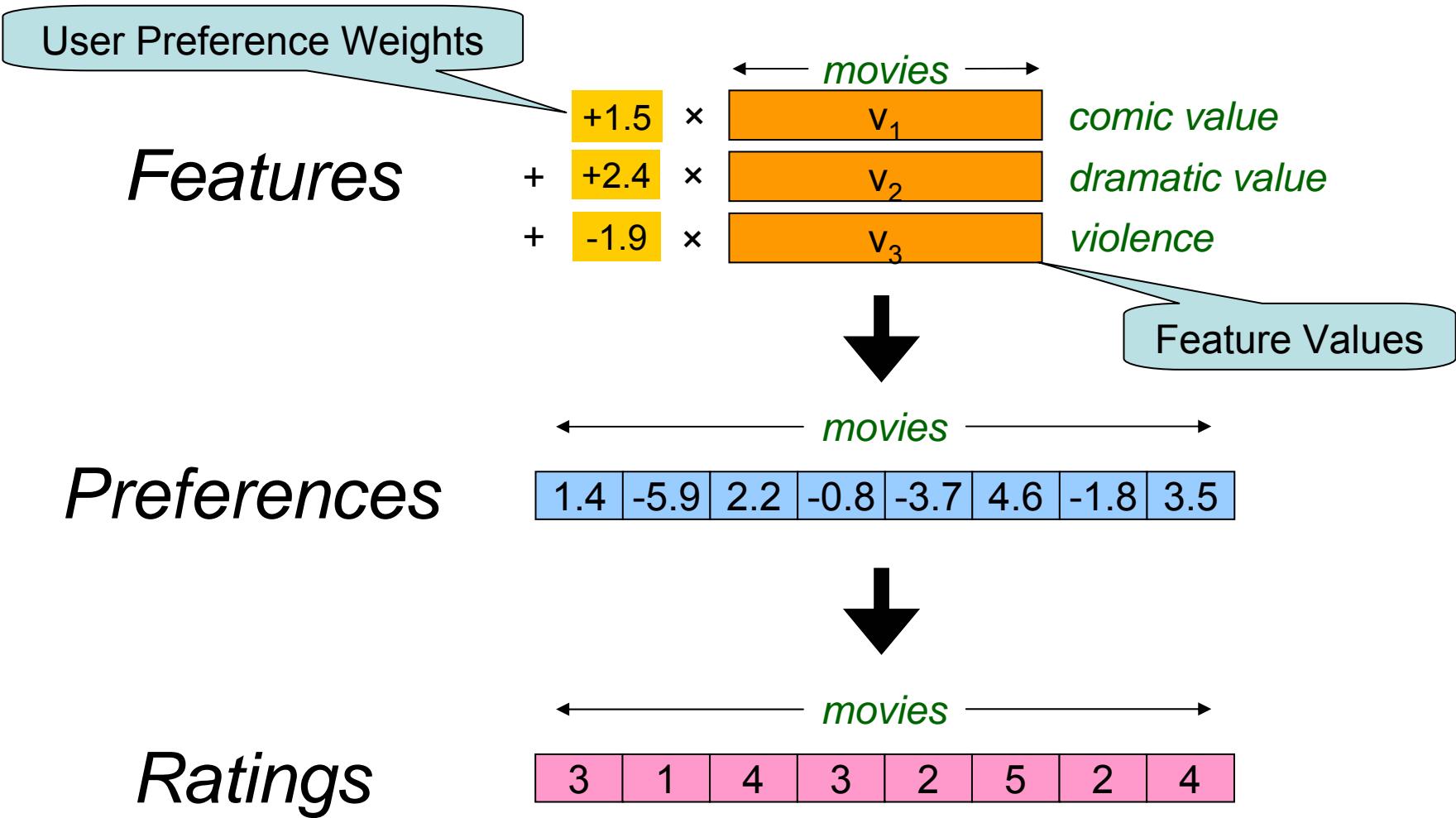
⇒ Predict unobserved entries “Will user i like movie j ?”

		movies							
		2	1	4			5		
		5	4		?	1		3	
		3	5	2					
		4	?	5	3		?		
		4	1	3		5			
		2		1	?				
		1		5	5	5		4	
		2	?	5	?	4			
		3	3	1	5	2		1	
		3		1		2		3	
		4	5	1		3			
		3		3	?		5		
		2	?	1	1				
		5		2	?	4		4	
		1	3	1	5	4		5	
		1	2	4		5	?		

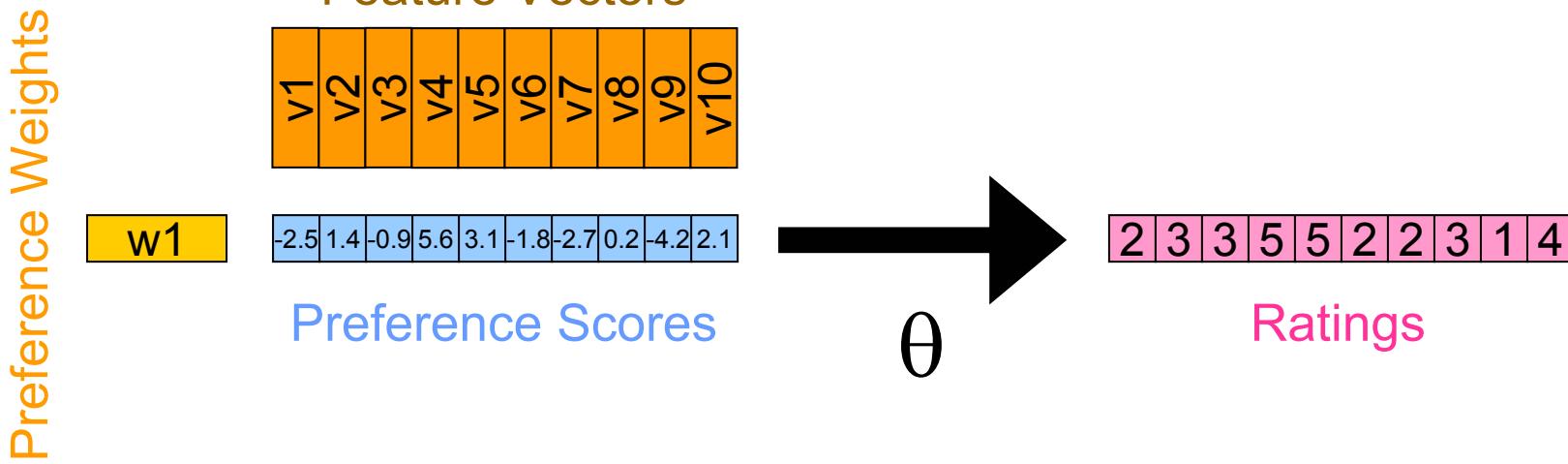
Problems to Address

- Underlying representation of preferences
 - Norm constrained matrix factorization (MMMF)
- Discrete, ordered labels
 - Threshold-based ordinal regression
- **Scaling-up MMMF to large problems**
 - **Factorized objective, gradient descent**
- *Ratings may not be missing at random*

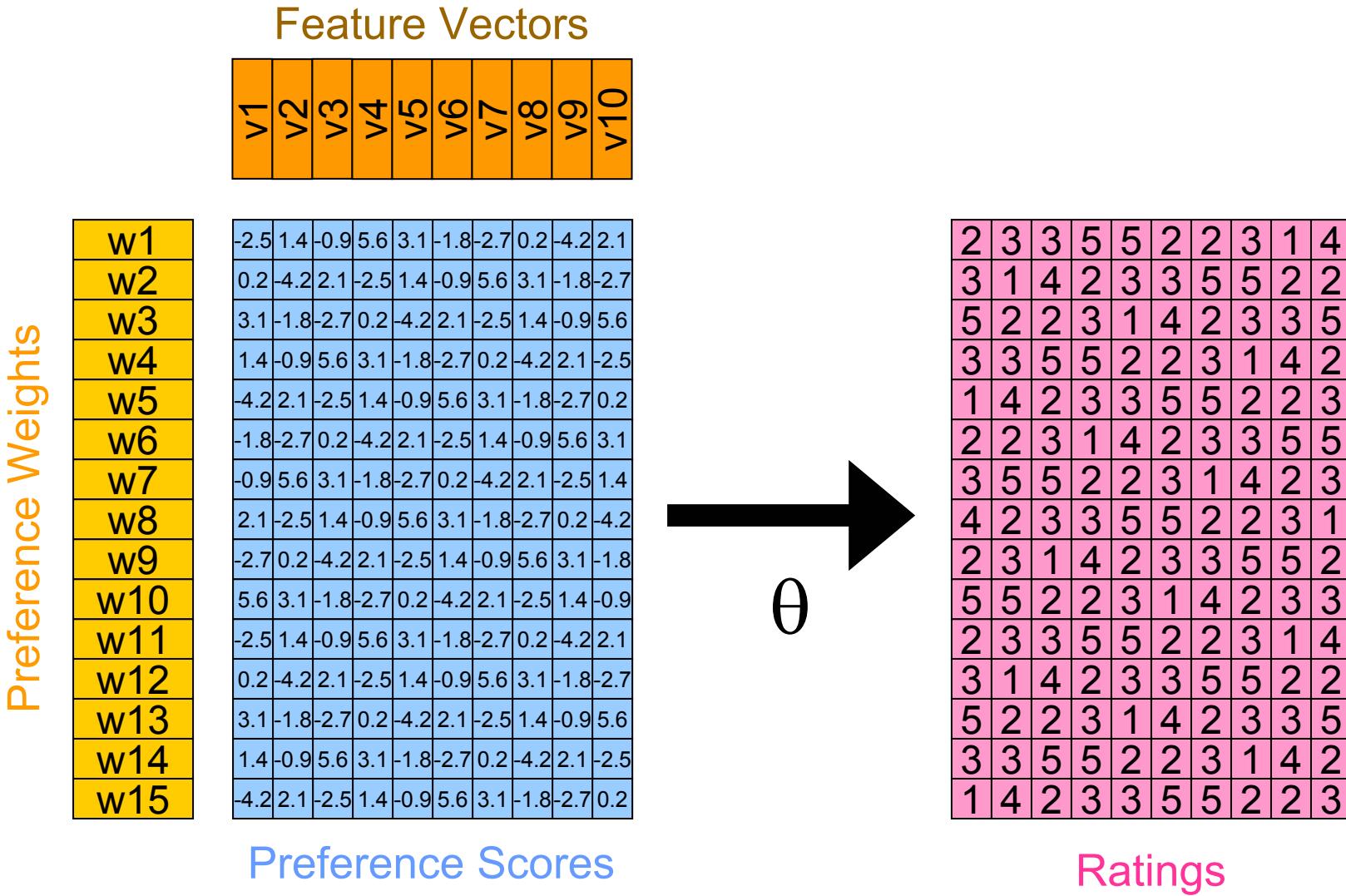
Linear Factor Model



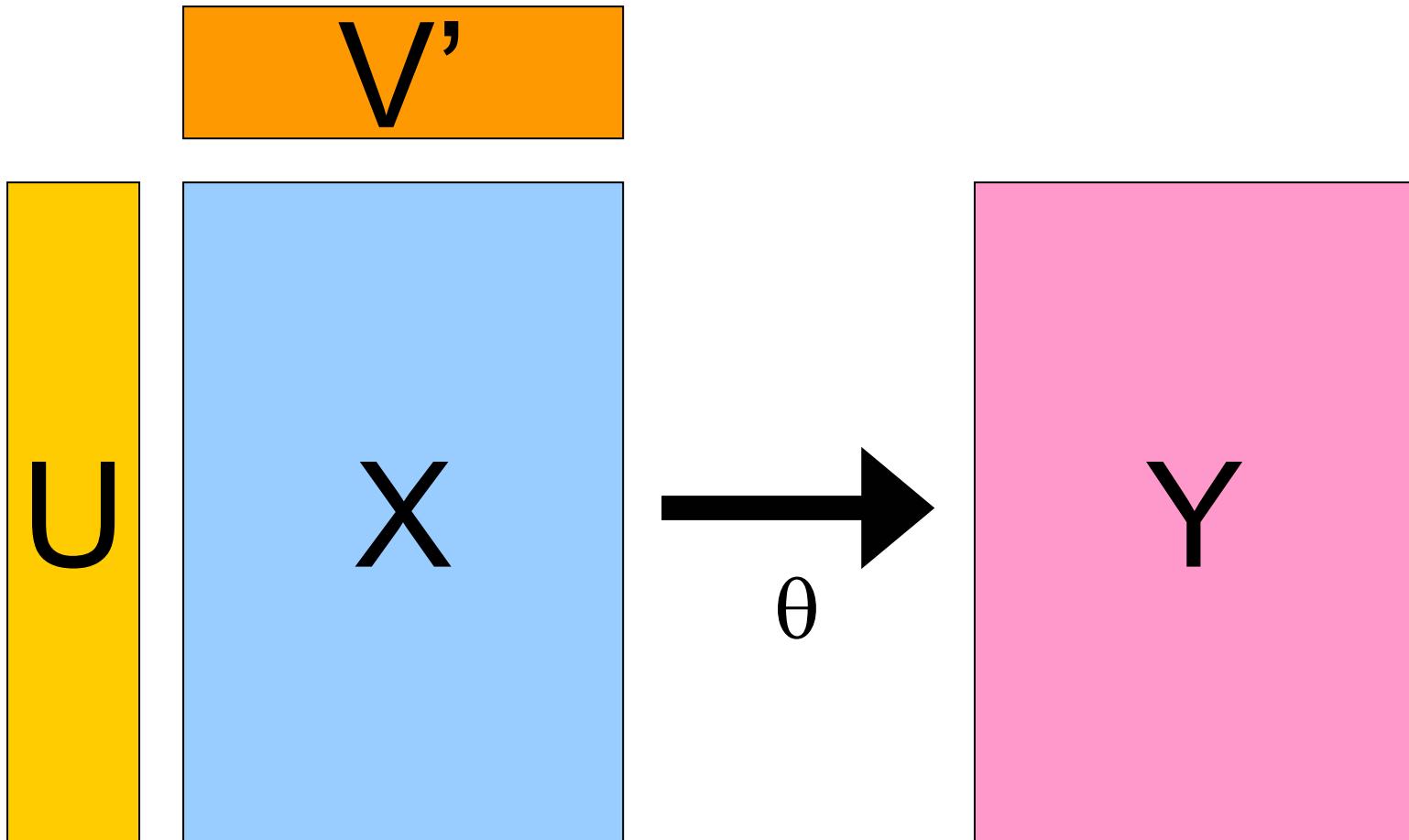
Ordinal Regression



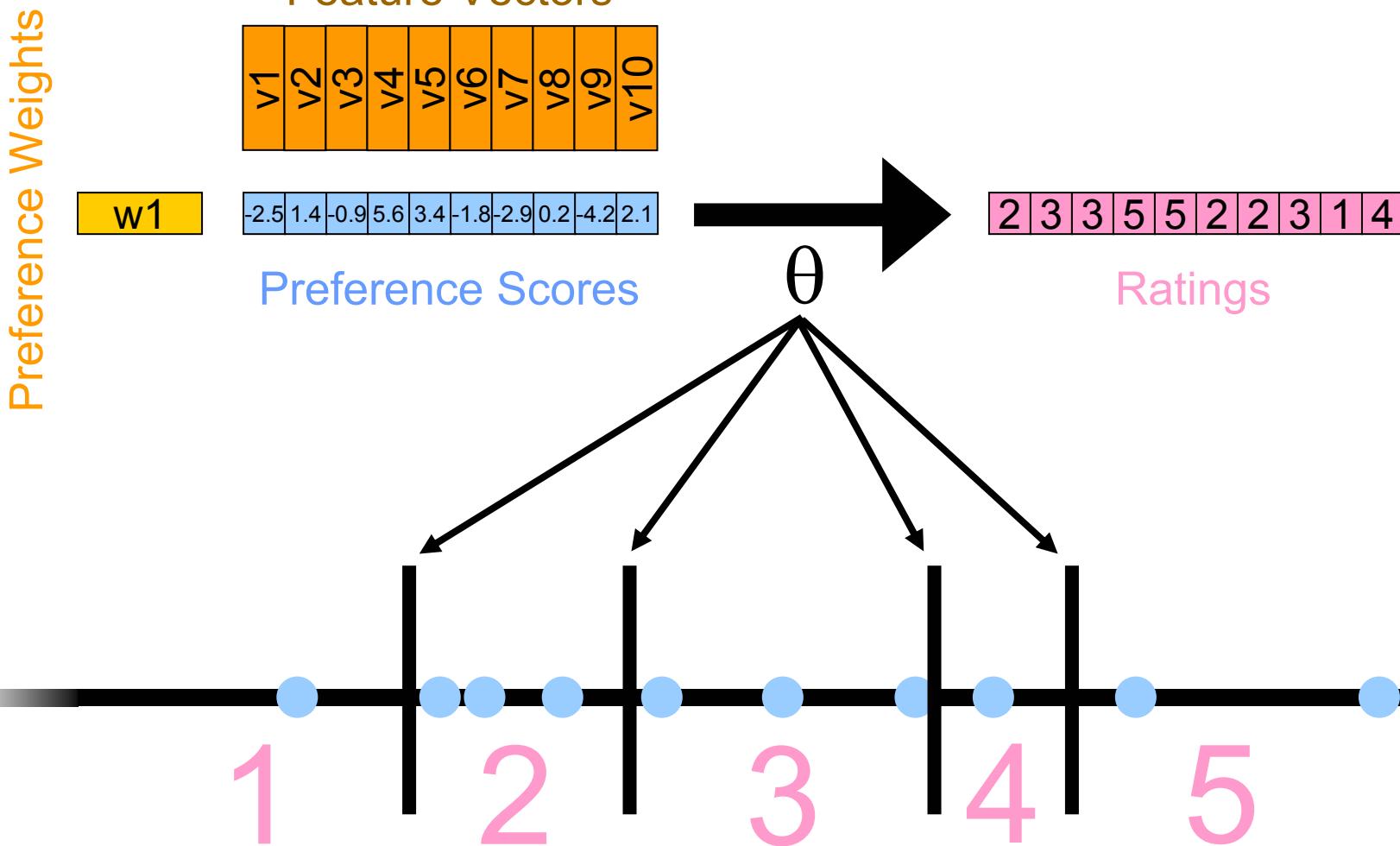
Matrix Factorization



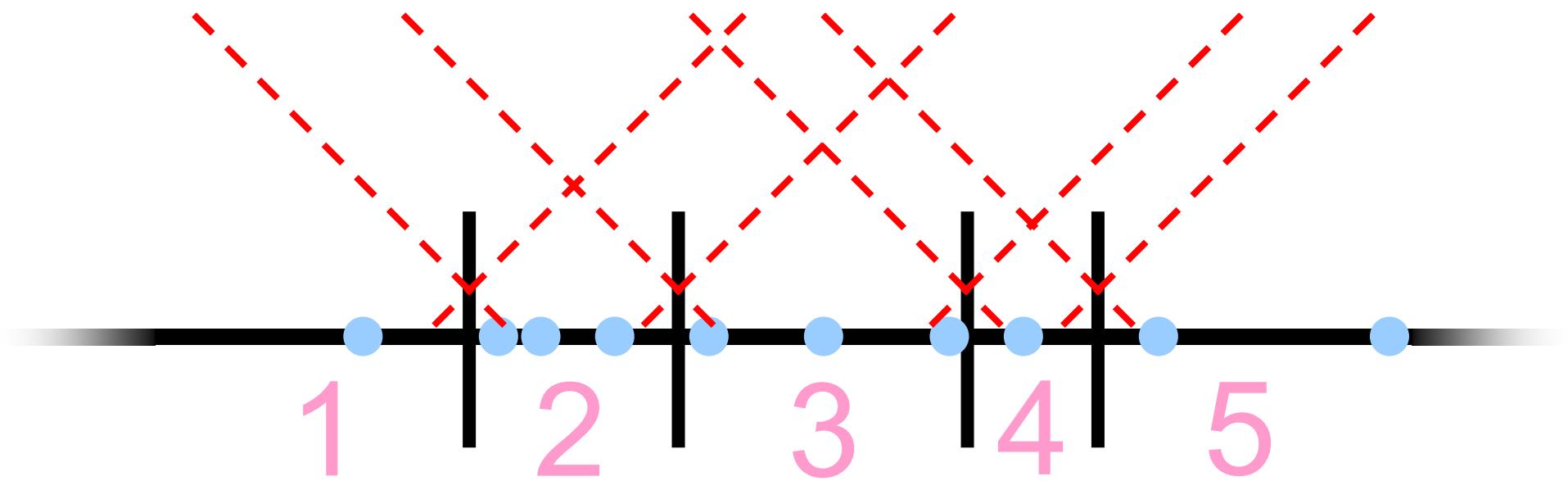
Matrix Factorization



Ordinal Regression



Max-Margin Ordinal Regression

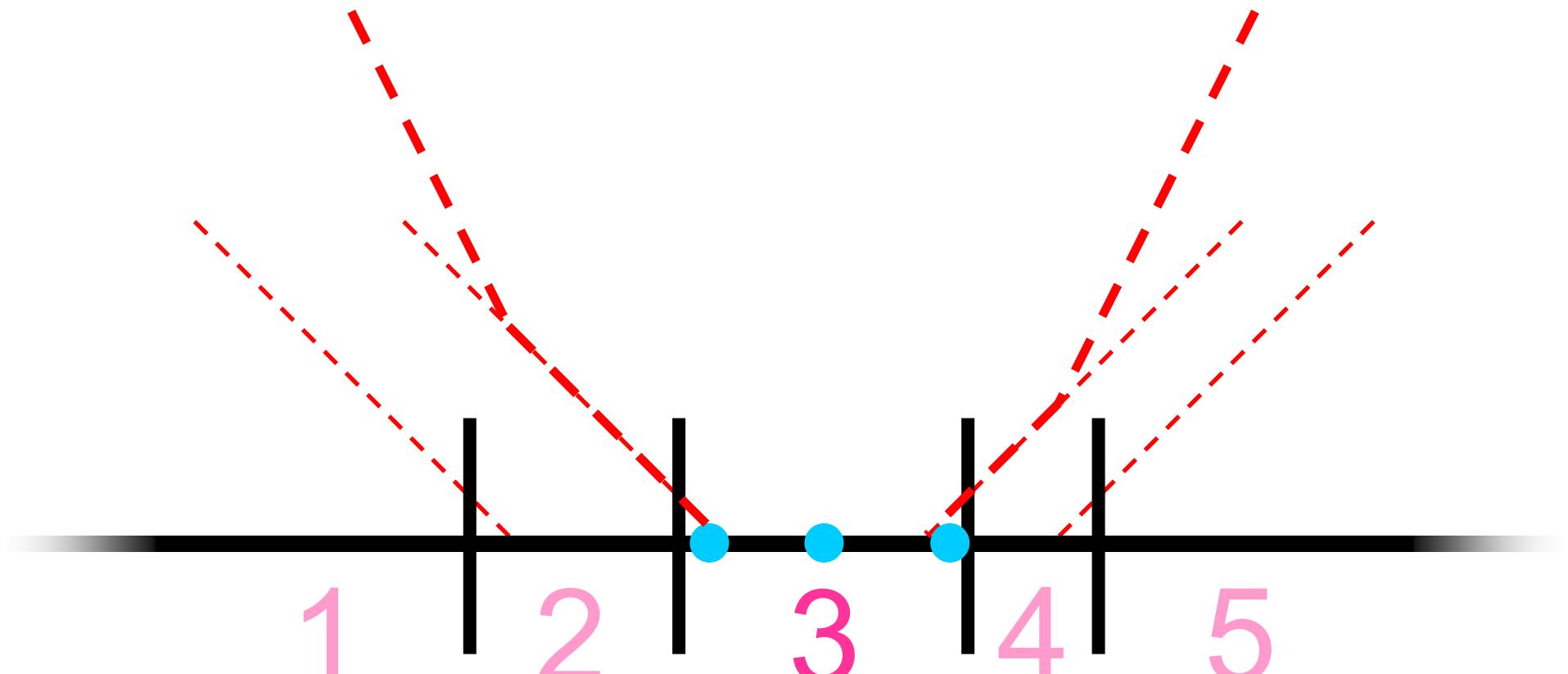


[Shashua & Levin, NIPS 2002]

Absolute Difference

- Shashua & Levin's loss bounds the misclassification error
- Ordinal Regression: we want to minimize the absolute difference between labels

All-Thresholds Loss



[Srebro et al., NIPS 2004]

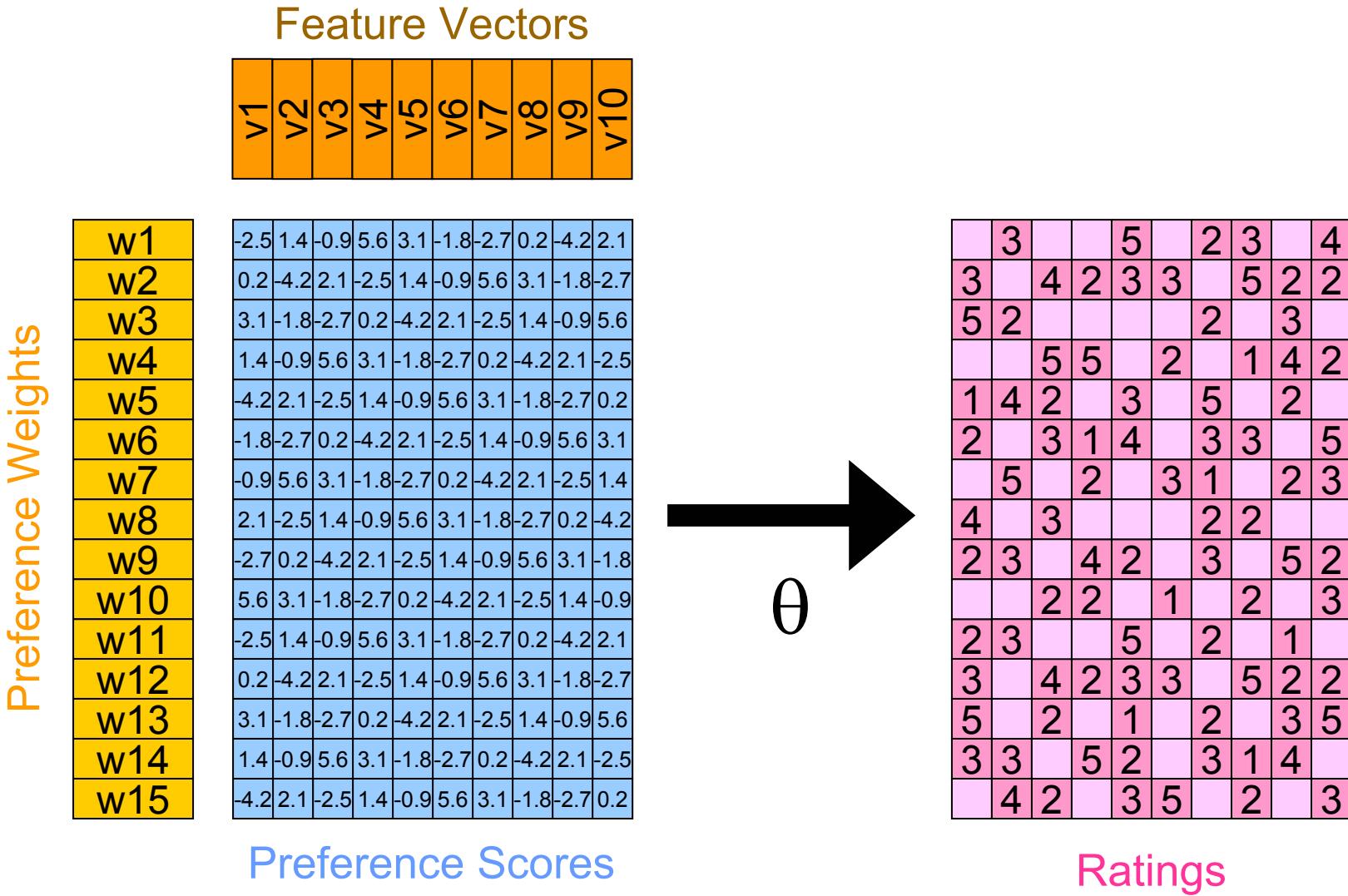
[Chu & Keerthi, ICML 2005]

All-Thresholds Loss

- Experiments comparing:
 - Least squares regression
 - Multi-class classification
 - Shashua & Levin's Max-Margin OR
 - All-Thresholds OR
- All-Thresholds Ordinal Regression
 - Lowest misclassification error
 - Lowest absolute difference error

[Rennie & Srebro, IJCAI Wkshp 2005]

Learning Weights & Features



Low Rank Matrix Factorization

	2	4	5	1	4	2	
3	1		2	2	5		4
4	2		4	1	3	1	
3		3	4	2			4
2	3	1	4	3		2	
	2	2	1		4		5
	2	4	1	4	2	3	
1	3	1	1		4	3	
	4	2	2	5	3	1	

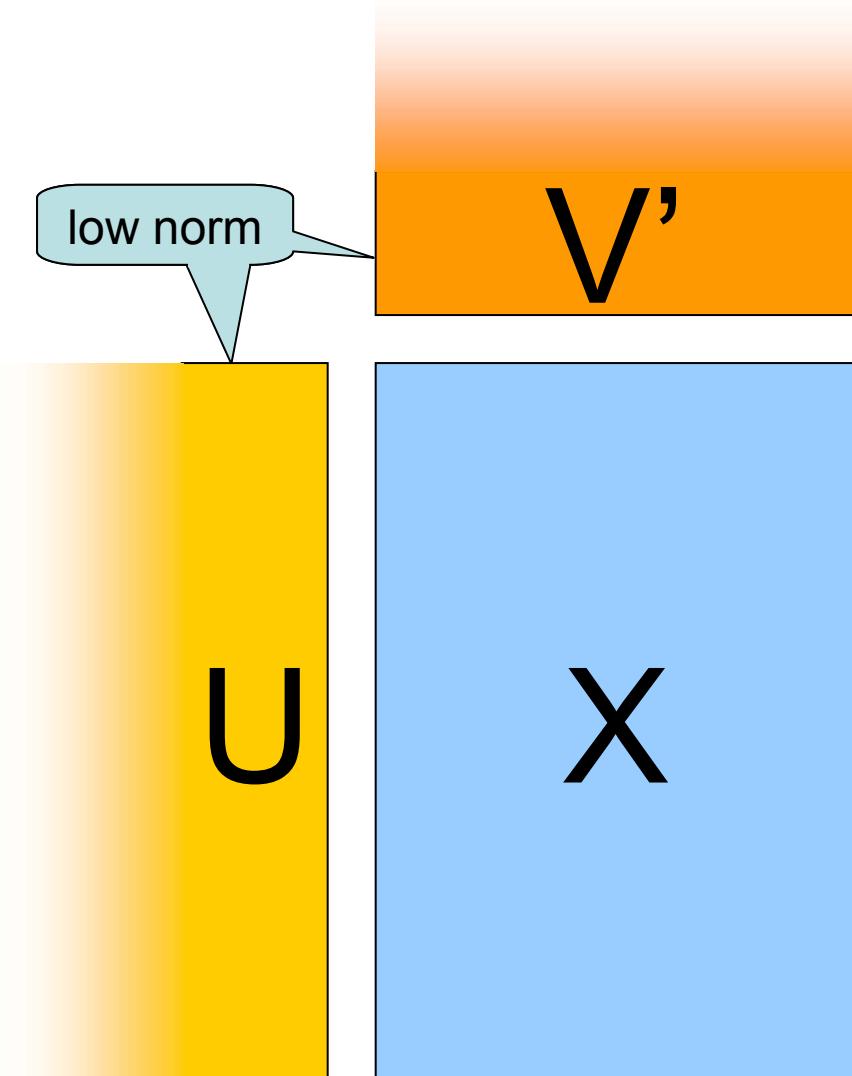
$$Y \approx U \times V' = X^{\text{rank } k}$$

- Sum-Squared Loss
- Fully Observed Y
- Classification Error Loss
- Partially Observed Y

Use SVD to find Global Optimum

Non-convex
No explicit soln.

Norm Constrained Factorization



$$\|X\|_{\text{tr}} = \min_{U,V} (\|U\|_{\text{Fro}}^2 + \|V\|_{\text{Fro}}^2) / 2$$

$$\|U\|_{\text{Fro}}^2 = \sum_{i,j} U_{ij}^2$$

[Fazel et al., 2001]

MMMF Objective

Original Objective

$$\min_X \|X\|_{\text{tr}} + c \text{ loss}(X, Y)$$

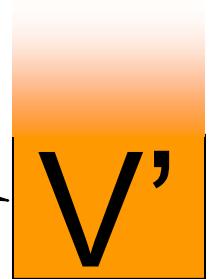
All-Thresholds

Factorized Objective

$$\begin{aligned} \min_{U,V} & (\|U\|_{\text{Fro}}^2 + \|V\|_{\text{Fro}}^2)/2 \\ & + c \text{ loss}(UV', Y) \end{aligned}$$

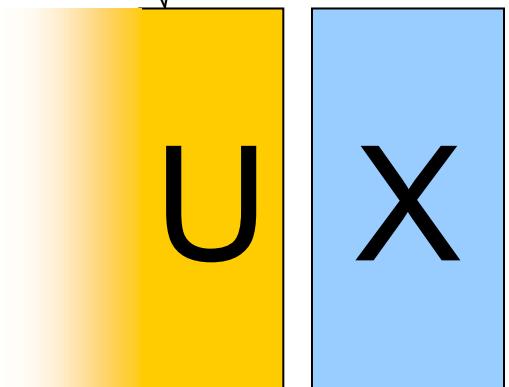
All-Thresholds

low norm



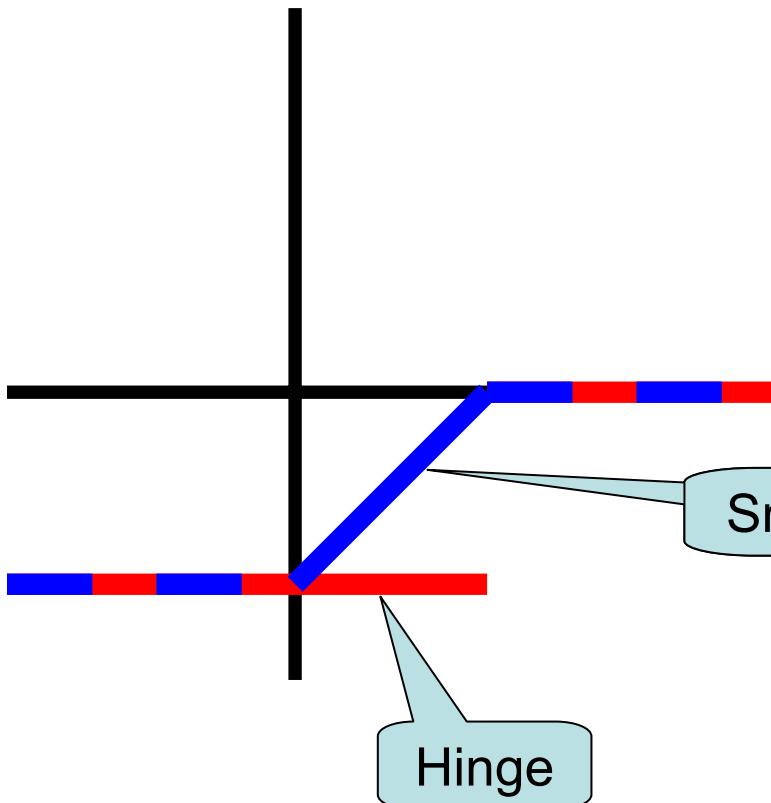
[Srebro et al., NIPS 2004]

$$\|U\|_{\text{Fro}}^2 = \sum_{i,j} U_{ij}^2$$

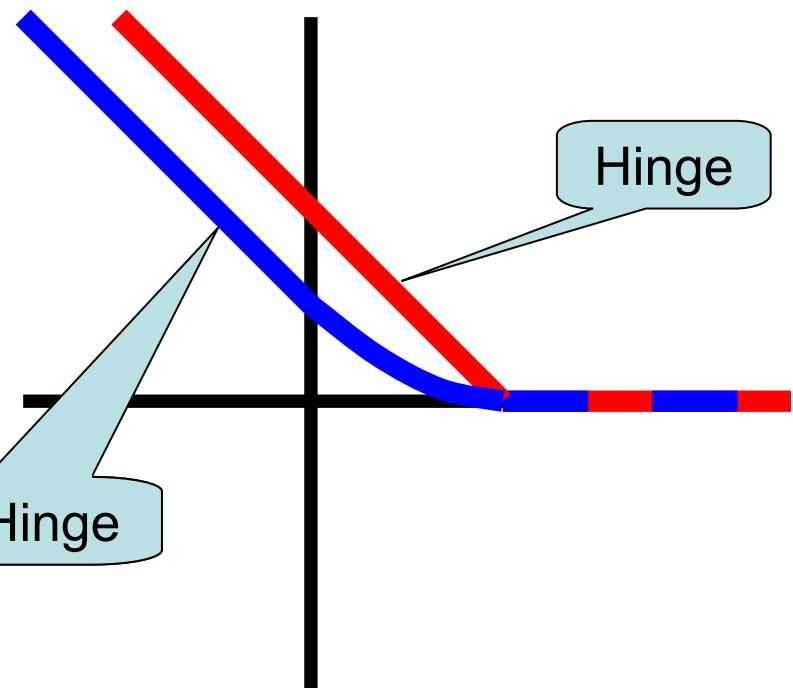


Smooth Hinge

Gradient



Function Value



Collaborative Prediction Results

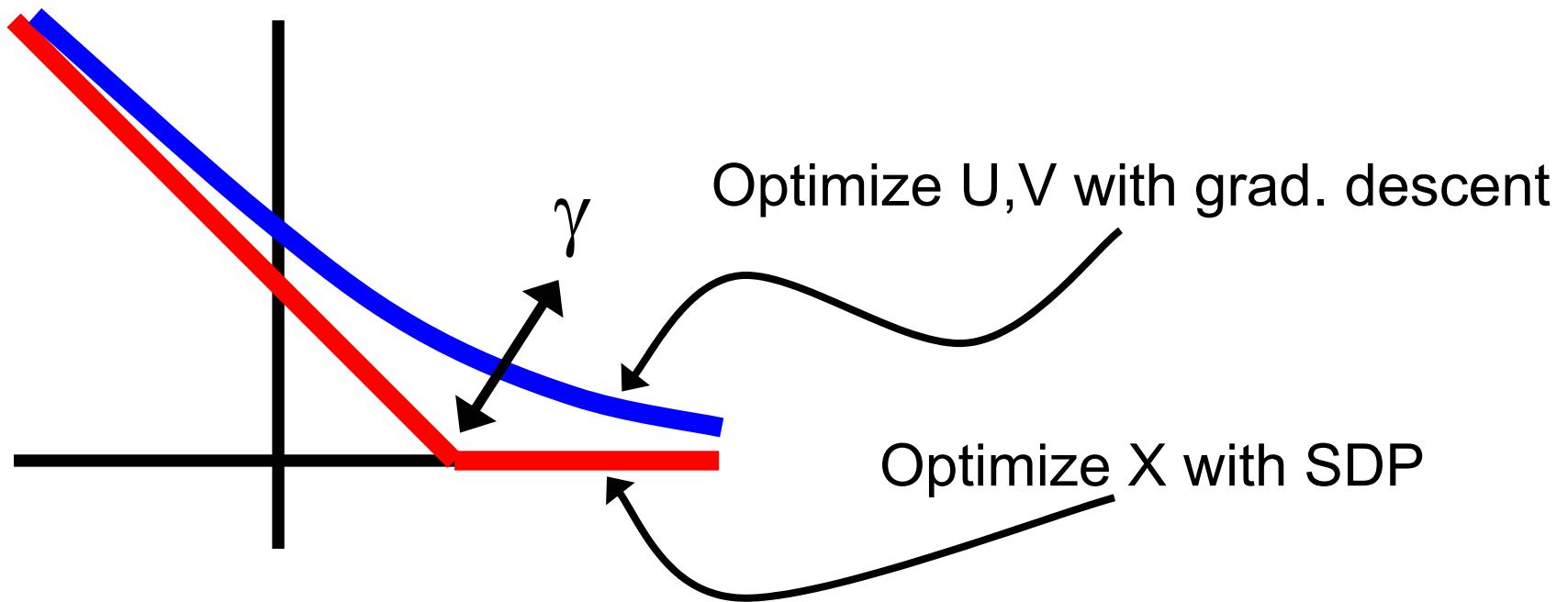
		EachMovie		MovieLens	
size, sparsity:		36656x1648, 96%		6040x3952, 96%	
Algorithm	Weak	Strong	Weak	Strong	
	Error	Error	Error	Error	
URP	.4422	.4557	.4341	.4444	
Attitude	.4520	.4550	.4320	.4375	
MMMF	.4397	.4341	.4156	.4203	

URP & Attitude Results: [Marlin, 2004]

Local Minima?

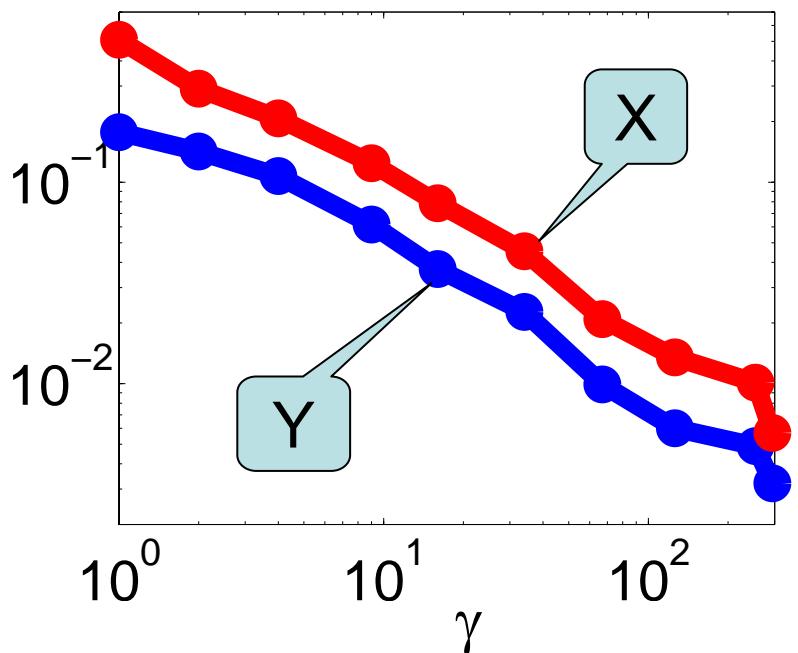
Factorized Objective

$$\min_{U,V} (\|U\|_{\text{Fro}}^2 + \|V\|_{\text{Fro}}^2)/2 + c \text{ loss}(UV', Y)$$

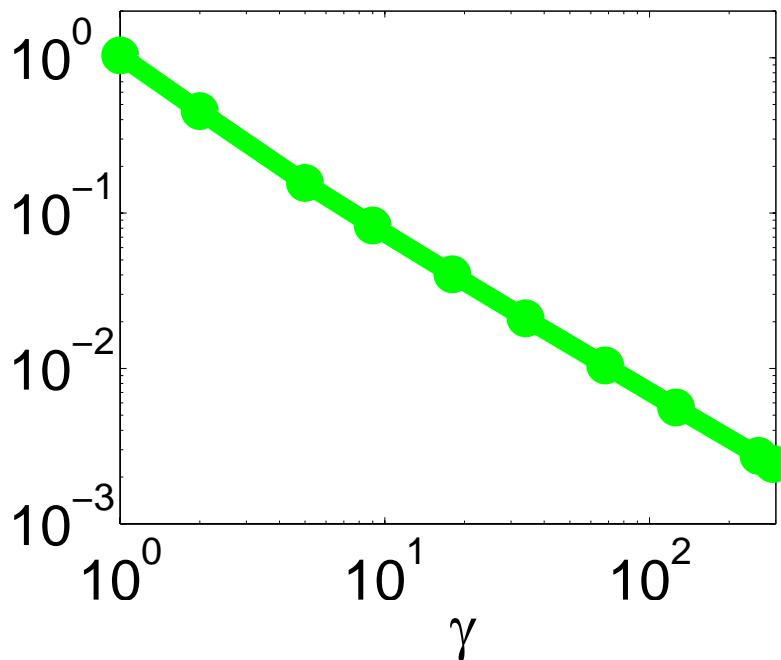


Local Minima?

Matrix Difference



Objective Difference



Data: 100 x 100 MovieLens, 65% sparse

Summary

- We scaled MMMF to large problems by optimizing the Factorized Objective
- Empirical tests indicate that local minima issues are rare or absent
- Results on large-scale data show substantial improvements over state-of-the-art

D'Aspremont & Srebro: large-scale SDP optimization methods. Train on 1.5 million binary labels in 20 hours.