Learning & Inference in Graphical Models Monday, March 28, 2011

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Monday, Wednesday, Friday 1:30-2:20

http://ttic.uchicago.edu/~rurtasun/courses/GraphicalModels/graphical_models.html

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Course Outline

 Book: Probabilistic Graphical Models, Daphne Koller, Nir Friedman (in library)

Part I: Models

Chapter 2: Basic Notions.

Chapter 3: Bayesian Networks.

Chapter 4: Undirected Graphical Models.

Course Outline

Part II: Inference

Chapters 9&10&11: Exact Inference

Chapter 12: Sampling methods for Inference.

Chapter 13: MAP inference

Course Outline

Part III: Learning

Chapter 17: Parameters Estimation

Chapter 18: Learning Structure

Chapter 19: Partially Observed Data

Causality: Chapter 21 (if time permits)

Course load

- Homework: 50% of the grade.
 6-7 exercises.
 2 programming exercises.
- Exam: 50% of the grade.
- No mid-term exam.

Background - Probability

- The confidence that an event will occur
- "there is a 30% chance of rain"
- "Tossing coin, there is a 50% probability for 'head'"
- Probability Space:
- I) What are the possible <u>events</u>?

2) How we **measure** each event?

Probability

- What are the possible outcomes ?
 Coin toss: Ω = {"head", "tail"}
 Die: Ω = {1,2,3,4,5,6}
- **Event** is subset of outcomes $S \subset \Omega$:

Examples for die: {1,2,3}, {2,4,6}, ...

How we <u>measure</u> each event?

Probability function.

Probability Function

- Assign non-negative weight for atomic events
- $\ {}^{{}_{\bullet}}$ Probability of event $\ S\subset \Omega$

$$P(S) = \sum_{\omega \in S} P(\omega)$$

Examples for die: $P({2,4,6}) = P(2)+P(4)+P(6)$

• Claim: $P(S_1 \cup S_2) = P(S_1) + P(S_2) - P(S_1 \cap S_2)$

Probability Function

Overall weight is one

$$\sum_{\omega \in \Omega} P(\omega) = 1$$

Coin: P("head") + P("tail")=I

Die: P(I)+P(2)+P(3)+P(4)+P(5)+P(6)=I

Conditional Probability

- SI,S2 are independent if $P(S_1 \cap S_2) = P(S_1)P(S_2)$
- Conditional Probability: $S \subset \Omega$ $P(S_1|S) = P(S_1 \cap S)/P(S)$ • Claims: $\sum_{\omega \in S} P(\omega|S) = 1$ If SI,S are independent then $P(S_1|S) = P(S_1)$

Conditional Probability

Claim (Chain Rule):

 $P(S_1 \cap S_2 \cap \dots \cap S_n) = P(S_1)P(S_2|S_1) \cdots P(S_n|S_1, \dots, S_{n-1})$

Joint distribution

- Given two spaces: Ω_1, Ω_2 (e.g. coin, die, two dice)
- Joint probability function

$$P(\omega_1, \omega_2) \ge 0, \qquad \sum_{\omega_1 \in \Omega_1, \omega_2 \in \Omega_2} P(\omega_1, \omega_2) = 1$$

Induces marginal probability functions

$$P(\omega_1) = \sum_{\omega_2 \in \Omega_2} P(\omega_1, \omega_2)$$

Random Variable

- A random variable is a function, which maps events or outcomes (e.g., the possible results of rolling two dice: (1, 1), (1, 2), etc.) to real numbers (e.g. their sum)
- A discrete random variable have a discrete set of values
 $X(\omega) \in \{r_1, ..., r_n\}$
- A discrete random with n value induces a probability space with n elements.

$$P(r) = P(X = r) = P(\{\omega : X(\omega) = r\})$$

Joint Distribution

Two random variables induce a joint distribution

 $P(r_1, r_2) = P(X_1 = r_1, X_2 = r_2) = P(X_1 = r_1 \text{ and } X_2 = r_2)$

Joint distribution induces a marginal distribution $P(X_1 = r_1) = \sum_{r_2} P(X_1 = r_1, X_2 = r_2)$ Two random variables are independent X₁⊥X₂ if $P(X_1 = r_1, X_2 = r_2) = P(X_1 = r_1)P(X_2 = r_2)$

Conditional Distribution

Conditional distribution:

 $P(X_1|X_2 = r_2) = P(X_1, X_2 = r_2) / P(X_2 = r_2)$

- Claim: If two random variables are independent then $P(X_1|X_2) = P(X_1)$
- Three random variables are conditionally independent $X_1 \perp X_2 | X_3$ if

 $P(X_1 = r_1, X_2 = r_2 | X_3 = r_3) = P(X_1 = r_1 | X_3 = r_3) P(X_2 = r_2 | X_3 = r_3)$

Expectation, Variance

- Expectation $\mathbb{E}[X] = \sum_{r} P(X = r) \cdot r$
- Variance

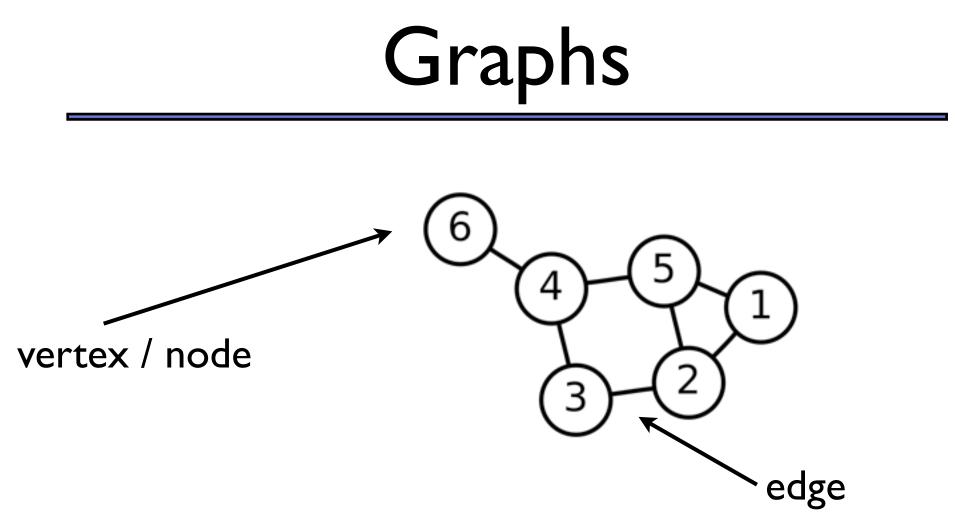
$$V[X] = \sum_{r} P(X = r)(r - \mathbb{E}[X])^2 = \mathbb{E}[X^2] - (\mathbb{E}[X])^2$$

Continuous Random Var

A continuous random variable have has a density function f(r)

$$P(X(\omega) \in [r_1, r_2]) = \int_{r_1}^{r_2} f(r)$$

- Expectation $\mathbb{E}[X] = \int_r f(r) \cdot r$
- Variance $V[X] = \mathbb{E}[X^2] (\mathbb{E}[X])^2$

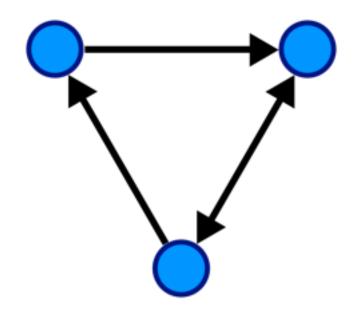


● G=(V,E)

- The edges are not directed (called undirected graph)
- undirected graph without cycles is called tree

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Direct Graphs



 Directed graph without cycles is direct a cyclic graph (DAG)

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