Learning & Inference in Graphical Models Monday, March 30, 2011

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Monday, Wednesday, Friday 1:30-2:20

http://ttic.uchicago.edu/~rurtasun/courses/GraphicalModels/graphical models.html

Motivation: Medical Diagnostic

Probability p(d,x1,...,xn) over symptoms and diseases:

 $\times I = 0$ if patient has no fever. $\times I = I$ if patient has fever.

x2=0 if patient does not cough. x2=1 otherwise.

d is a disease: flu, ear infection, lung infection, ...

Given the symptoms, what is the probability of a disease?

Given the symptoms, what is the probability of a disease?

p(flu | cough, fever) >? p(no flu | cough, fever)

- Problems:
- I) There are exponentially many entries in the probability distribution (at least 2ⁿ possibilities). Each entry typed need to be compared to other entries.
- 2) One need to marginalize out the diseases. Summing over exponentially many elements.

Independence

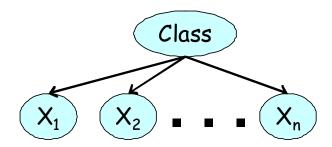
If x I,...,xn are independent then

$$p(x_1,...,x_n) = p(x_1)\cdots p(x_n)$$

2ⁿ entries can be described by 2n numbers

Naive Bayes

- d= is a disease name
- x I,...,xn are the patient symptoms.
- Assume $X_1 \perp \cdots \perp X_n | D$
- $p(d, x_1, ..., x_n) = p(d)p(x_1|d) \cdots p(x_n|d)$



The experts need to type D+2nD entries.

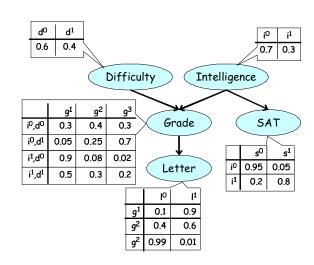
Naive Bayes

Prediction is efficient:

$$\frac{p(d = flu|x_1, ..., x_n)}{p(d = ear|x_1, ..., x_n)} = \frac{p(d = flu)}{p(d = ear)} \prod_{i=1}^n \frac{p(x_i|d = flu)}{p(x_i|d = ear)}$$

Statistical assumptions are too restrictive.

A way to describe a joint probability



$$p(I, D, G, S, L) = p(I)P(D)p(G|I, D)p(S|I)p(L|G)$$

Chain Rule:

$$p(I, D, G, S, L) = p(I)P(D|I)p(G|I, D)p(S|I, D, G)p(L|I, D, G, S)$$

Implicit independence statements!

$$p(I, D, G, S, L) = p(I)P(D)p(G|I, D)p(S|I)p(L|G)$$

Chain Rule:

$$p(I, D, G, S, L) = p(I)P(D|I)p(G|I, D)p(S|I, D, G)p(L|I, D, G, S)$$

Independence statements:

$$D \perp I$$
, $S \perp \{D, G\} | I$, $L \perp \{I, D, S\} | G$

$$p(I, D, G, S, L) = p(I)P(D)p(G|I, D)p(S|I)p(L|G)$$

Independence statements:

$$D\bot I, \quad S\bot \{D,G\}|I, \quad L\bot \{I,D,S\}|G$$

- Claim: A variable is independent from its non-descendants given its parents.
- Result: There are more independence in the graph, e.g. $S \perp \{D,G,L\}|I$

$$p(I, D, G, S, L) = p(I)P(D)p(G|I, D)p(S|I)p(L|G)$$

ullet proof of: $S \perp \{D,G,L\}|I$

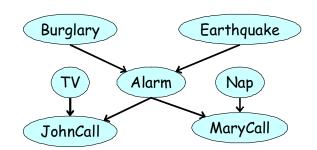
$$p(D,G,S,L|I) =? p(S|I)p(D,G,L|I)$$

$$p(D, G, L|I) = \frac{p(I, D, G, L)}{p(I)} = \frac{\sum_{S} p(I, D, G, S, L)}{p(I)}$$

$$p(S|I) = \frac{p(I,S)}{p(I)} = \frac{\sum_{G,D,L} p(I,D,G,S,L)}{p(I)}$$

For general

directed graphs:



$$p(x_1, ..., x_n) = \prod_{i=1}^{n} p(x_i | x_{parents(i)})$$

 Bayesian network encodes conditional independencies

$$x_i \perp x_{non-descendants(i)} | x_{parents(i)}$$

Independency Maps

given a distribution p(x1,...,xn), we denote by l(p) its independency map, i.e. all statements of the form

$$X_I \bot X_J | X_K$$
 for $I, J, K \subset \{1, ..., n\}$

The directed graph gives some of the independencies of the distribution, through separation in directed graphs.