Lecture 10 CNNs on Graphs CMSC 35246: Deep Learning

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CMSC 35246



Two Scenarios

- For CNNs on graphs, we have two distinct scenarios:
 - Scenario 1: Each data point lives in \mathbb{R}^d , but the dataset has an underlying graph structure

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 - Scenario 1: Each data point lives in \mathbb{R}^d , but the dataset has an underlying graph structure
 - Each coordinate is a value associated with a vertex of underlying graph
 - For images: The underlying graph is always a grid of fixed dimensions
 - Scenario 2: Each data point is itself a graph (Example regression task: Molecules as input, boiling points as output)
 - Each graph can be of different size
 - Sub-problem: Given a graph \mathcal{G} , find an embedding $\phi: \mathcal{G} \to \mathbb{R}^p$

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Scenario 1

CNNs on data in irregular domains



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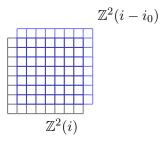
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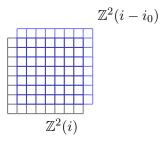
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- In general the grid can be \mathbb{Z}^d
- CNNs are able to exploit various structures that reduce sample complexity
 - Translation structure (allowing use of filters)
 - Metric on the grid (allows compactly supported filters)
 - Multiscale structure of the grid (allows subsampling)

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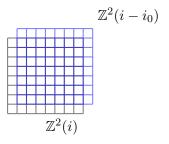


- $\bullet\,$ The translation group acts on \mathbb{Z}^2
- We are able to exploit this symmetry of the grid in CNNs

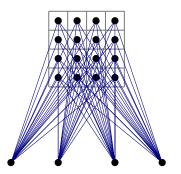


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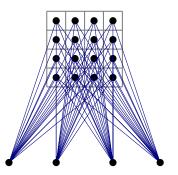


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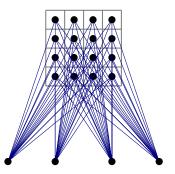


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- With k filters, each with support S we have O(kS) (independent of n)
- Using multiscale nature, we can pool, and reduce the number of parameters further

Data on Irregular Domains

• Often we can have *structured* data defined over coordinates that does not enjoy any of these properties

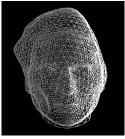


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- More: Social network data, protein interaction networks etc.



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- Example: 3-D mesh data (each coordinate might be surface tension)
- More: Social network data, protein interaction networks etc.
- In each case we again have n coordinates but which don't live on a regular grid

Figure source: Eurocom Face Modeling

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• We can think of a n dimensional image as a function defined on the vertices of a graph $\mathcal{G}=(\Omega,E)$ with $|\Omega|=n$



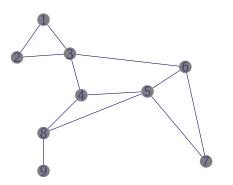


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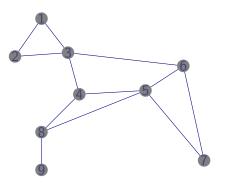


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- In general we can have signals defined over a general graph:



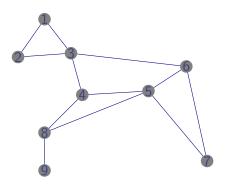
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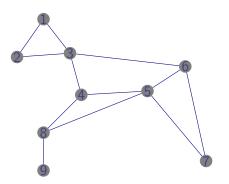
- Ω is the vertex set (input coordinates), $W_{i,j}$ the similarity between any two coordinates i and j
- Note: $W_{i,j}$ is similarity between coordinates, not datapoints

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- If the underlying graph structure is known, $W_{i,j}$ will be available
- If unknown: Need to estimate it from training data

Locally Connected Networks



Lecture 10 CNNs on Graphs

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- Number of parameters: O(Sn) (S is average neighbhorhood size)

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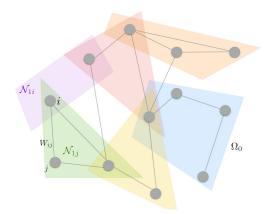
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- h is the non-linearity and L_k is the pooling operation

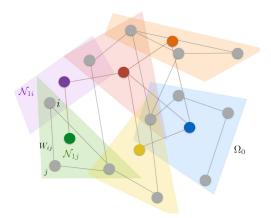


• Level 1 clustering

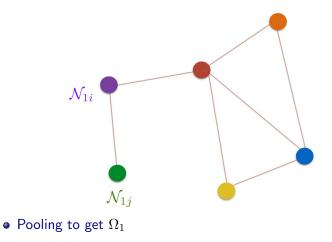
This and next few illustrations are by Joan Bruna



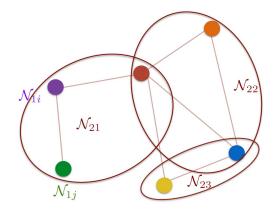
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• Pooling to get Ω_1



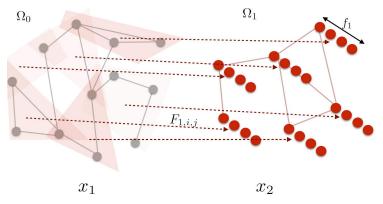
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• Level 2 clustering

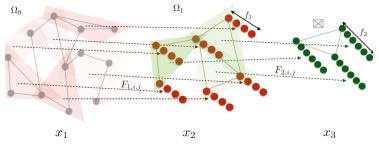


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• Multiple Feature maps: Level 1

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• Multiple Feature maps: Level 2



Lecture 10 CNNs on Graphs

Spectral Construction

Spectral Networks



Quick Digression: The Graph Laplacian



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Let U = [u₁,..., u_d] be the eigenvectors of L

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Graph Convolution in Frequency Domain

• Define convolution of input signal x with filter g on ${\mathcal G}$ as:

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• Learning filters on a graph \implies learning spectral weights:

$$x *_{\mathcal{G}} g = U^T(diag(w_g)Ux)$$
 with $w_g = (w_1, \dots, w_d)$



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- But we want filters that are local
- \bullet Observation: Smoothness in frequency domain \implies spatial decay
- Solution: Consider a smoothing kernel $\mathcal{K} \in \mathbb{R}^{d \times d_0}$ and search for multipliers:

$$w_g = \mathcal{K}\tilde{w}_g$$



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- Estimate it from data:
- Method 1: Unsupervised
 - Given dataset $X \in \mathbb{R}^{N \times d}$, compute distance d(i, j) between features:

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• Then compute
$$W_{i,j} = \exp^{-\frac{d(i,j)}{\sigma^2}}$$

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- Method 2: Supervised
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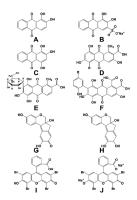
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• Use Gaussian kernel as before to get $W_{i,j}$

Scenario 2

Learning Embeddings of Graphs

Example Task: Regression



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- Input: Organic Compounds (graphs)
- Output: Boiling point

Graph Embedding: Simple Algorithm

Algorithm 1 Generation of embedding

Require: G = (V, E), radius δ , Hidden Weights: $H_1^1, \ldots, H_l^{\delta}$, Output Weights: W_1, \ldots, W_{δ} **Initialize:** Embedding $\phi \leftarrow 0$ **Initialize:** For every vertex $\mathbf{r}_v \leftarrow \Psi(v)$

(local vertex features)

- 1: for all L=1 to δ (for every layer) do
- 2: for each vertex v in graph do

3:
$$\mathbf{r}_1, \ldots, \mathbf{r}_N = \mathsf{neighbors}(v)$$

4:
$$v \leftarrow \mathbf{r}_v + \sum_{i=1}^N \mathbf{r}_i$$

5: $\mathbf{r}_v \leftarrow \sigma(v H_L^N)$

6:
$$\mathbf{i} \leftarrow \mathsf{softmax}(\mathbf{r}_v W_L)$$

7: Update:
$$\phi \leftarrow \phi + \mathbf{i}$$

- 8: end for
- 9: end for
- 10: Output embedding ϕ