# Lecture 10 CNNs on Graphs CMSC 35246: Deep Learning

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CMSC 35246



# **Two Scenarios**

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  - Scenario 1: Each data point lives in  $\mathbb{R}^d$ , but the dataset has an underlying graph structure

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- For CNNs on graphs, we have two distinct scenarios:
  - Scenario 1: Each data point lives in  $\mathbb{R}^d$ , but the dataset has an underlying graph structure
    - Each coordinate is a value associated with a vertex of underlying graph
    - For images: The underlying graph is always a grid of fixed dimensions
  - Scenario 2: Each data point is itself a graph (Example regression task: Molecules as input, boiling points as output)
    - Each graph can be of different size
    - Sub-problem: Given a graph  $\mathcal{G}$ , find an embedding  $\phi: \mathcal{G} \to \mathbb{R}^p$

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#### Scenario 1

#### CNNs on data in irregular domains



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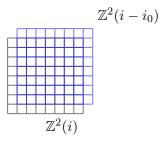
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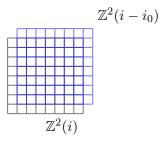
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  - Translation structure (allowing use of filters)
  - Metric on the grid (allows compactly supported filters)
  - Multiscale structure of the grid (allows subsampling)

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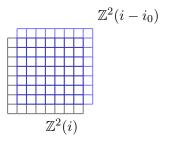


- $\bullet\,$  The translation group acts on  $\mathbb{Z}^2$
- We are able to exploit this symmetry of the grid in CNNs

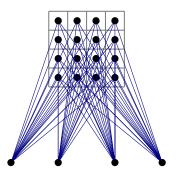


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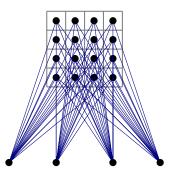


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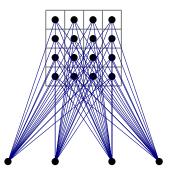


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- With k filters, each with support S we have O(kS) (independent of n)
- Using multiscale nature, we can pool, and reduce the number of parameters further

# Data on Irregular Domains

• Often we can have *structured* data defined over coordinates that does not enjoy any of these properties

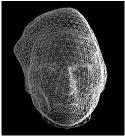


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- More: Social network data, protein interaction networks etc.



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- Example: 3-D mesh data (each coordinate might be surface tension)
- More: Social network data, protein interaction networks etc.
- In each case we again have n coordinates but which don't live on a regular grid

Figure source: Eurocom Face Modeling

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• We can think of a n dimensional image as a function defined on the vertices of a graph  $\mathcal{G}=(\Omega,E)$  with  $|\Omega|=n$ 



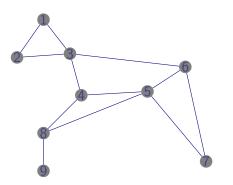


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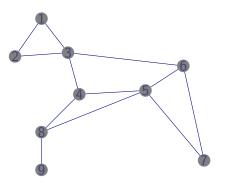


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- *G* just happens to be a grid graph with strong local structure which makes CNNs useful
- In general we can have signals defined over a general graph:



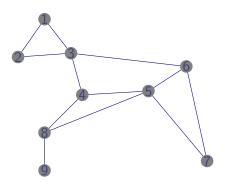
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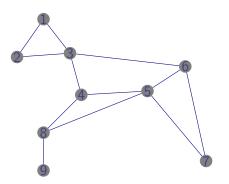
- $\Omega$  is the vertex set (input coordinates),  $W_{i,j}$  the similarity between any two coordinates i and j
- Note:  $W_{i,j}$  is similarity between coordinates, not datapoints

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- If unknown: Need to estimate it from training data

Locally Connected Networks



Lecture 10 CNNs on Graphs

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- Number of parameters: O(Sn) (S is average neighbhorhood size)

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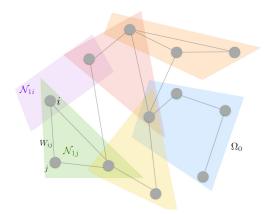
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- h is the non-linearity and  $L_k$  is the pooling operation

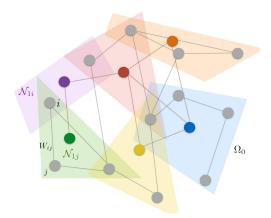


#### • Level 1 clustering

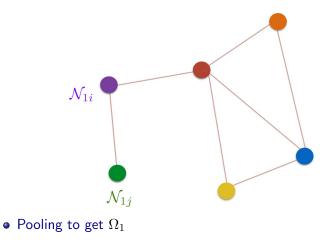
This and next few illustrations are by Joan Bruna



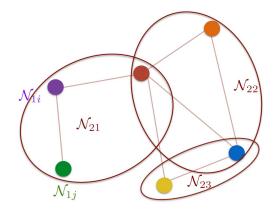
Lecture 10 CNNs on Graphs



• Pooling to get  $\Omega_1$ 



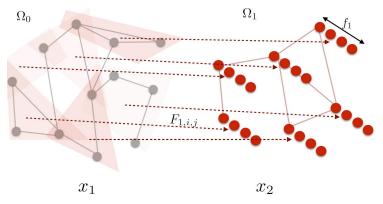
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• Level 2 clustering

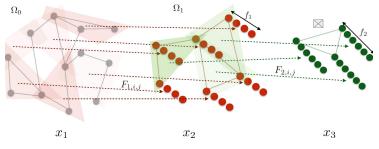


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• Multiple Feature maps: Level 1

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• Multiple Feature maps: Level 2



Lecture 10 CNNs on Graphs

#### Spectral Construction

Spectral Networks



#### Quick Digression: The Graph Laplacian



• Again consider  $W \in \mathbb{R}^{d \times d},$  the weighted adjacency matrix for  $\mathcal{G} = (\Omega, E)$ 

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Let U = [u<sub>1</sub>,..., u<sub>d</sub>] be the eigenvectors of L

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## Graph Convolution in Frequency Domain

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• Learning filters on a graph  $\implies$  learning spectral weights:

$$x *_{\mathcal{G}} g = U^T(diag(w_g)Ux)$$
 with  $w_g = (w_1, \dots, w_d)$ 



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- But we want filters that are local
- $\bullet$  Observation: Smoothness in frequency domain  $\implies$  spatial decay
- Solution: Consider a smoothing kernel  $\mathcal{K} \in \mathbb{R}^{d \times d_0}$  and search for multipliers:

$$w_g = \mathcal{K}\tilde{w}_g$$



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- Estimate it from data:
- Method 1: Unsupervised
  - Given dataset  $X \in \mathbb{R}^{N \times d}$ , compute distance d(i, j) between features:

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• Then compute 
$$W_{i,j} = \exp^{-\frac{d(i,j)}{\sigma^2}}$$

- Estimate it from data:
- Method 2: Supervised
  - Given dataset  $X \in \mathbb{R}^{N \times d}$  and labels  $y \in \{1, \dots, C\}^L$ , train a fully connected MLP with K layers, with weights  $W_1, \dots, W_K$

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  - Pass data through network, extract K layer features  $W_K \in \mathbb{R}^{N \times m_k}$ , then compute:

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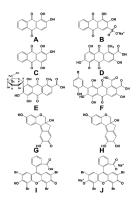
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• Use Gaussian kernel as before to get  $W_{i,j}$ 

#### Scenario 2

#### Learning Embeddings of Graphs

### **Example Task: Regression**



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- Input: Organic Compounds (graphs)
- Output: Boiling point

# Graph Embedding: Simple Algorithm

Algorithm 1 Generation of embedding

**Require:** G = (V, E), radius  $\delta$ , Hidden Weights:  $H_1^1, \ldots, H_l^{\delta}$ , Output Weights:  $W_1, \ldots, W_{\delta}$ **Initialize:** Embedding  $\phi \leftarrow 0$  **Initialize:** For every vertex  $\mathbf{r}_v \leftarrow \Psi(v)$ 

(local vertex features)

- 1: for all L=1 to  $\delta$  (for every layer) do
- 2: for each vertex v in graph do

3: 
$$\mathbf{r}_1, \ldots, \mathbf{r}_N = \mathsf{neighbors}(v)$$

4: 
$$v \leftarrow \mathbf{r}_v + \sum_{i=1}^N \mathbf{r}_i$$

5:  $\mathbf{r}_v \leftarrow \sigma(v H_L^N)$ 

6: 
$$\mathbf{i} \leftarrow \mathsf{softmax}(\mathbf{r}_v W_L)$$

7: Update: 
$$\phi \leftarrow \phi + \mathbf{i}$$

- 8: end for
- 9: end for
- 10: Output embedding  $\phi$